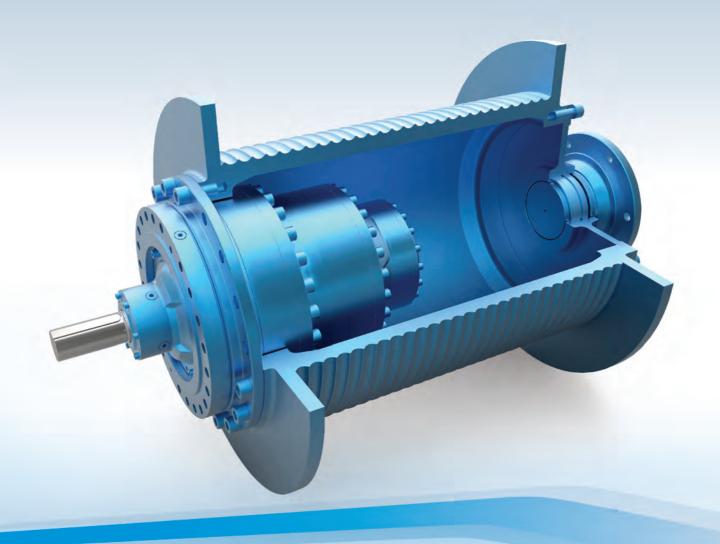


BONENG



博肯 PW 行星内藏式卷扬齿轮箱 PW Winch Gearbox

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07/2017

PW行星内藏式卷扬齿轮箱

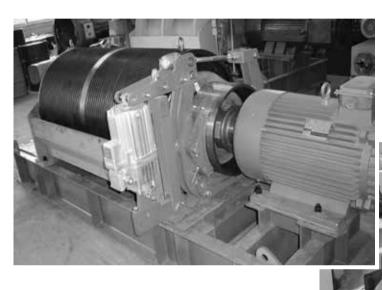
PW winch gearbox



- ◆ PW行星内藏式卷扬齿轮箱是卷扬机构的理想驱动装置。结构紧凑,可直接安装于卷筒内部,节省空间,特别是在空间窄小的情况下,它是更经济的解决方案。在繁重工作条件和恶劣环境下能提供卓越的品质和性能,并经受过考验。
- ◆ 太阳轮、行星轮均采用优质合金钢渗碳淬火处理,内齿圈采用优质合金钢表面硬化处理,所有齿轮均磨齿加工。
- ◆ 行星架和内齿圈连接法兰均采用球墨铸铁材料,且均通过计算机模拟变形和应力分析等 优化设计。
- ◆ 所有轴承采用知名品牌,轴承系统承载能力高,安全裕度大。
- ◆ 输入、输出采用径向骨架油封及V型密封,在复杂和恶劣的工作环境中具有更高的安全性和更长的使用寿命。
- ◆ 高度的模块化设计,批量生产更加经济,有效提高供货速度。
- ◆ 两级、三级和四级行星齿轮传动设计,速比覆盖范围广。
- ◆ 运转噪音低,传动效率高,使用寿命长。
- ◆ 安装简单,维护方便。
- PW winch gearbox is the perfect driven device for hoisting winches. Compact dimensions is useful to assemble the PW winch gearbox in the drum and save the space. Especially in the confined space conditions, it is the economic solutions. Boneng PW winch gearbox have proved highly successful under extreme bad operating conditions.
- Sun and planet wheels material is excellent alloy steel and processed by carburization and quenching. Internal gear wheel material is excellent alloy steel and processed by hardening. All gears grinding.
- The connection flange of planet carrier and internal gear wheel are made of ductile graphite iron. Optimal design through the computer and the stress analysis.
- All bearings are from famous brand. The bearings have high loading support and safety.
- The input and output are protected with radial shaft seals and V type seals. Viton material improves the seal life.
- High modular design. Volume production is more economic and speeds up the delivery period.
- ◆ 2 stage, 3 stage and 4 stage design and wide range of ratio.
- ◆ Low noise, high efficiency and long operation life.
- Easy mounting and maintenance.







港口起重机和船厂 随车吊和汽车吊 建筑起重机和输送设备 货运和工作电梯 舰船和甲板起重机 集装箱龙门吊 汽车和履带式起重机 海上平台起重机 Harbour and dockyard cranes Mobile cranes Construction cranes and conveyors Material and working elevators Shipboard and deck cranes Container gantries

Crawling crane
Offshore cranes

博能公司全系列产品采用独创的模块化设计,零部件通用最大化,具有量产优势,标准零配件成本低,供货周期短,整个产品系列均采用高制造标准,保证了极好的承载能力和工作可靠性。

All series products of Boneng use the original modular design, parts general maximization, it has advantage of mass production, the standard parts of low costs, short delivery cycle. The whole product series adopt high manufacturing standards to ensure the excellent carrying capacity and working reliability.

注意事项! 必须严格遵守以下各项! Note: You must conform to the following instructions

- ◆ 样本中的结构示意图、外形图及其他附图只属范例,无严格比例要求。(未注尺寸单位均为mm)。
- ◈ 所注重量仅为平均值,并不具有约束力。
- ◆ 为防止意外事故发生,所有旋转部件均按照使用者所在国家和地区的安全规范由购置方加罩保护。
- ◆ 试车之前必须认真阅读使用说明书。
- ◆ 齿轮箱在供货时已处于准运行状态,运行前需加注润滑油。
- ◆ 说明书中注油量只作为参考值,实际注油量应以油镜上的标记为准。
- 润滑油粘度应按齿轮箱使用工况及使用环境温度选取。
- ◆ 只能采用国际知名品牌的润滑油。
- ◆ All the construction figures, dimension drawings and other drawings in the catalogue are only the examples, no strict scale defined. (The unmarked dimension units are mm)
- The marked weight is only the average value, no binding.
- ◆ To avoid the accident, all the rotation components should be covered by customer according to the local safety regulations and laws.
- Read the instructions carefully before operating.
- Fill the lubrication oil before running.
- ◆ The oil quantity in the instructions is only for reference. The actual oil value should be done as the oil glass level.
- The adhesiveness of lubrication is depended on the operating condition and the ambient temperature.
- Only choose the international famous brand lubrication oil.

产品功能标识/The functional label of gearbox



油 镜 /Oil glass



通气帽 /Breather



进油孔 /Oil filler



放油孔 /Oil drain

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1 结构简图

1 Design and Construction

二级行星传动齿轮箱

额定输出扭矩: 11.6至155kN·m 钢丝绳负载: 67至408KN 公称减速比13至28 齿轮箱内置于滚筒 输入与输出旋转方向相反

2 stage planetary gearbox

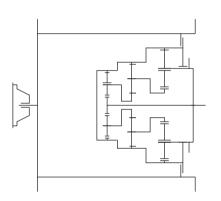
Output torques: 11.6 to 155 KN.m

Rope load: 67 to 408KN

Ratio from i=13 to 28

Gearbox mounted inside winch drum.

Input and output in opposite sense of rotation



三级行星传动齿轮箱

额定输出扭矩: 25至236kN·m 钢丝绳负载: 116至566KN 公称减速比45至141 齿轮箱内置于滚筒 输入与输出旋转方向相反

3 stage planetary gearbox

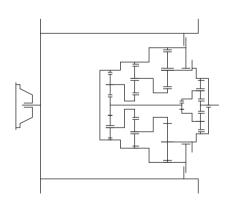
Output torques: 25 to 236 KN.m

Rope load: 116 to 566 KN

Ratio from i=45 to 141

Gearbox mounted inside winch drum.

Input and output in opposite sense of rotation



四级行星传动齿轮箱

额定输出扭矩: 47至1500kN·m 钢丝绳负载: 180至1950KN 公称减速比167至940 齿轮箱内置于滚筒 输入与输出旋转方向相反

4 stage planetary gearbox

Output torques: 47 to 1500 KN.m

Rope load: 180 to 1950 KN

Ratio from i=167 to 940

Gearbox mounted inside winch drum.

Input and output in opposite sense of rotation

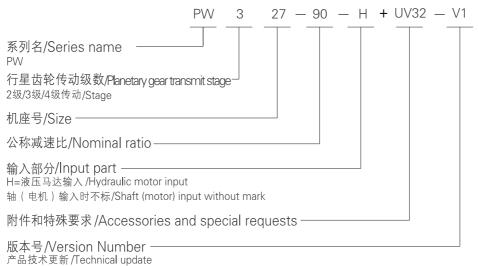
备注: 各级传动的机械效率为98%,钢丝绳滚筒轴承及密封圈的机械效率为99%。

例如: 两级行星卷扬机的总机械效率为η=0.98x0.98x0.99=0.95

Remark: Mechanical efficiency of every stage is 98%, bearings for rope drum and the seal rings mechanical efficiency is 99% For example: the total mechanical efficiency for 2 stage winch planetary gearbox $\eta = 0.98 \times 0.98 \times 0.99 = 0.95$

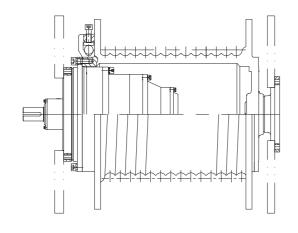
2 型号表示

2 Type description

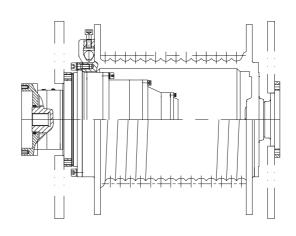


3 输入方式

3 Input modes



电机输入,水平安装/Motor input foot mounted



液压马达输入,水平安装/Hydraulic motor input, foot mounted

产品配备电动机、液压马达两种模块化输入系统。 液压马达输入时,输入轴为DIN 5480规格的花键轴,带具 有压力释放弹簧装置的液压多片式驻车制动系统。该制动 安全装置是独立的活塞或制动器,其释放压力最小为 15bar,最大承压为300bar,系统残留压力小于0.5bar。

备注:PW全系列行星齿轮内藏式卷扬齿轮箱可适配各种马达,如高速马达(单个或2—3个驱动单元)、摆线马达、低速大扭矩马达,能满足客户不同的应用与需求,具体使用请垂询。

PW with electric motor input and hydraulic motor input.

When hydraulic motor is input, the input shaft is a DIN 5480 spline shaft, equipped with the hydraulic pressure release and loose—spring multi disc brake parking system. This brake safety device is a self contained piston or brake with a minimum release pressure of 15 bar, the maximum pressure is 300 bar. System residual pressure is less than 0.5 bar.

Remark: PW complete range can be equipped with kinds of motors, such as high speed motor (Single or 2-3 drive units), cycloidal motor, low speed with big torque motor etc, can meet customer's different demands. For details, please consult Boneng.

4卷筒概述

4.1 卷筒种类:

- 1) 标准沟槽卷筒(图1)和特殊沟槽卷筒(图2)。
- 2) 沟槽方向分左旋和右旋,默认为右旋(图1)。
- 3) 特殊沟槽卷筒可避免多层缠绕时的乱绳现象,因为 每层钢丝绳的交叉点在滚筒截面的同一位置上,并 且确定了下一层钢丝绳的螺旋升角,可缠绕八层或 更多层。

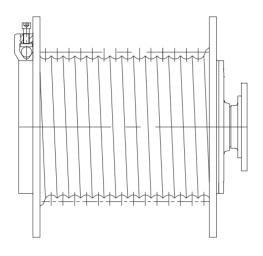


图1/Figure 1

4.2 钢丝绳固定方式: 在滚筒侧壁外侧

4 Integrated Rope Drum

4.1 Drum categories:

- 1) Drum with normal grooves (figure 1) and with special grooves (figure 2).
- 2) Rope groove has right hand lead and left hand. The default lead is right hand (figure 1).
- 3) Drum with special grooves can avoid the difficulties encountered in multi-layer winding on to grooves of the usual kind. As the crossover points of the rope in each layer always lie in the same section of the drum and the spiral angle of the next layer rope is determined. 8 and more layers can be accommodated without difficulty.

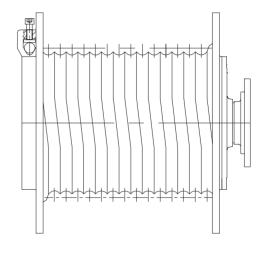


图2/Figure 2

4.2 Rope fixing: on the outside of the drum flange

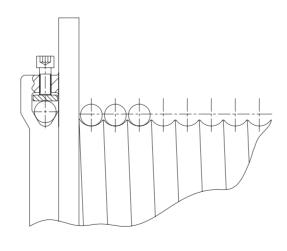
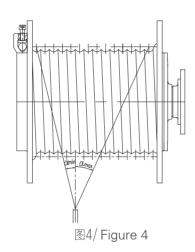


图3/Figure 3

4.3 为了保证钢丝绳正常缠绕,要求绳偏折角 α 维持在允许范 4.3 To achieve acceptable rope winding, the deflection angle 围之内(图4),应注意以下几点:

- 1) 钢丝绳的捻转方向应与卷筒沟槽方向相反。
- 2) 绳偏折角α不应小于0.5°,以防钢丝绳在侧壁处堆 积,保证钢丝绳分层缠绕。
- 3) 绳偏折角 α 不应大于1.5° ,为了使钢丝绳在第一层不 受与绳槽方向相反的拉力, 保证多层缠绕时钢丝绳在 滚筒挡板之间均匀的分布。
- α must be kept in the allowable value (figure 4)Attent the following points:
 - 1) Rope lay should be in the opposite sense to drum lead.
 - 2) The deflection angle α must not less than 0,5° in order to prevent the rope from riding up the drum flange and to ensure that it is guided securely on to the next layer.
 - 3) The deflection angle α must not exceed 1,5° in order to prevent the rope in the first layer being pulled against the grooves and, where a number of layers occur, to enable even winding up to the drum flanges.



4.4 卷筒和钢丝绳相关计算(图5): 卷筒直径D1=20xd或按客户要求 券筒法兰直径: D2=D1+2(Z+1)d 钢丝绳绳长(包含三圈过放保险钢丝绳): 4.4 The related calculations between drum and rope (figure 5): Rope drum diameter D1= 20 x d or as specified Drum flange diameter D2 = D1 + 2 (Z + 1) dLength of rope (including 3 safety turns)

Ls =
$$(\frac{L2}{P} - a)$$
 (D1+0.866 *d (Z-1)) $\frac{Z^* \pi}{1000}$

Ls:钢丝绳绳长(m)

L2: 卷筒长度或两挡板间距(mm)

D1: 卷筒直径 (mm)

d: 钢丝绳直径(mm)

p: 绳槽螺旋升角或节距(mm)

Z: 钢丝绳缠绕层数

a: 标准沟槽卷筒a=1; 特殊沟槽卷筒a=0.5

LS = Length of rope [m]

L2 = Length of drum [mm]

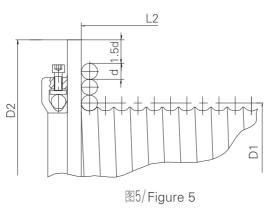
D1 = Diameter of drum [mm]

d = Diameter of rope [mm]

p = Pitch of rope groove [mm]

z = Number of rope layers

a = 1 for normal grooves, a= 0,5 for special grooves



5 阀块说明

根据卷扬的不同使用工况,需要在驱动马达上配备一 些辅助阀块来保证卷扬安全、正常的工作。

卷扬驱动马达用阀块分为两种:一种是用于开式液压系统的马达集成阀块:该阀块将负载平衡、缓冲压力冲击、制动器自动开启等功能集成在一起;一种是用于闭式液压系统的管路防爆安全阀:该阀块主要可在管路爆裂时锁住马达,防止马达失速。

5.1开式系统马达用阀块

马达集成阀块作为卷扬驱动马达用标准阀块,优先推 荐客户使用此阀块。如果客户只使用该阀块中的一种功 能,则需要进行非标设计。

5.1.1马达集成阀块

卷扬驱动马达用集成阀块具有缓冲压力冲击、平衡负值负载、刹车制动打开等功能,阀块原理图:平衡阀位于马达B侧油口(图6)、平衡阀位于马达A侧油口(图7)。

当马达A口进油时卷扬进行放绳则选择图6所示阀块; 当马达B口进油时卷扬进行放绳则选择图7所示阀块。

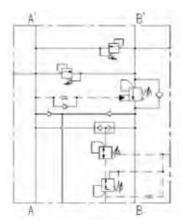


图6 马达集成阀块 Figure 6 motor integrated valve

阀块功能说明:

- 1) 卷扬在吊装作业时承受负值负载,为保证卷扬在承受负值负载时依然能平稳运行,不出现失速,需要在马达上安装平衡阀。
- 2) 卷扬在使用时,随着钢丝绳拉力的变化,负载不平稳容易导致液压系统压力波动,并出现较高的压力峰值,为了防止压力过高损坏液压马达,需要应用缓冲阀释放压力峰值。
- 3)卷扬停止工作时为保证卷扬可靠锁至,不出现遛钩现象,需要在卷扬上安装制动器。马达集成阀块中的刹车开启功能可实现制动器在卷扬工作时自动打开、停止工作时自动关闭。

备注: 阀块中平衡阀的安装方位至关重要,至于如何确定马达A侧、还是B侧安装平衡阀,可参考: 滚筒旋转方向说明。

5 Valve explanation

According to different working condition, the drive motor should be equipped with the valve to make sure the hoisting winch running safely.

There are two different valves:One is the motor integrated valve with open hydraulic system. The valve can control the load while it is descending, lighten the pressure and opening the brake automatically. Another is the tube explosion—proof valve with close hydraulic system. The valve can lock the motor when the tube is exploded and prevent the fail save motor.

5.1The motor integrated valve with open hydraulic system

The motor integrated valve is the standard valve for the hoisting winch drive, we suggest the customer to use the valve in advance. If customer need only use one of the valve function, it should be customized.

5.1.1 Motor integrated valve

The motor integrated valve can lighten the pressure, control the load and open the integrated motor brake automatically. Valve working principle drawing: the balance valve is on the oil port B side of motor (figure 6), the balance valve is on the oil port A side of motor (figure 7).

When filling the oil on motor A side and pull the rope, should select the valve as figure 6; When filling the oil on motor B side and pull the rope, should select the valve as figure 7.

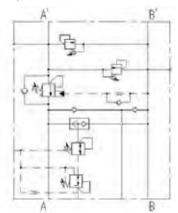


图7 马达集成阀块 Figure 7 motor integrated valve

Valve function:

- 1) When the hoisting winch is operating under negative loading, we should mount the balance valve on the motor to prevent the hoisting winch from stalled glide and keep the stable operating.
- 2) When the rope pulling force is changing and the load is unstable, it will cause the hydraulic pressure wave and there is the higher pressure, we should mount the cushion valve to release the pressure to prevent the hydraulic system damaged.
- 3) Brake is mounted to prevent the hoisting winch from slipping when the hoisting winch stops running and is locked well. The brake in the motor integrated valve can open automatically when the hoisting winch is operating and will close automatically when the hoisting winch is stopping.

Remark: the balance valve mounting position is very important. How to confirm the mounting position is on the A side or B side of motor, you can refer to the winding direction on the rope drums.

5.2闭式系统马达用阀块

闭式系统可通过液压泵实现静液压制动, 由发动机吸收 制动扭矩, 一般不推荐使用平衡阀, 以防止系统液压油温 度过高,如果客户有特殊需要,需进行技术论证。

5.2.1管路防爆安全阀块

为了保证客户安全的使用卷扬设备,推荐客户使用管路 防爆安全阀。该阀块可在液压管路发生爆裂时,切断马达 回油口,依靠马达回油口背压对马达进行动态制动,防止 卷扬失速,重物下坠。

管路防爆安全阀块原理图: 防爆安全阀位于马达A侧油 口(图8)、防爆安全阀位于马达B侧油口(图9)。

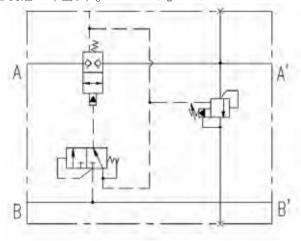
5.2The motor integrated valve with close hydraulic system

The close hydraulic system can achieve the hydrostatic brake through the hydraulic pump, and motor can absorb the brake torque, usually balance valve is not suggested to keep from the hydraulic oil temperature too high. If customer has this special demand, the technical testing should be done.

5.2.1 The tube explosion-proof valve

To ensure the correct using hoisting winch, we suggest customer to use the tube explosion—proof valve. It can cut off the returned oil port of motor when the hydraulic tube is split. The counter pressure of the returned oil port will make the dynamic brake on the motor to prevent the hoisting winch from slipping.

The tube explosion—proof valve working principle drawing: the tube explosion—proof valve is on the oil port A side of motor (figure 8), the tube explosion—proof valve is on the oil port B side of motor (figure 9).



管路防爆安全阀 图8 Figure 8 The tube explosion-proof valve

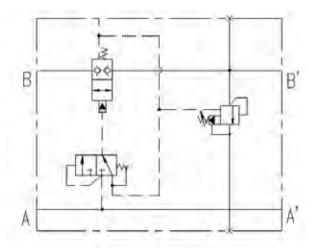


图9 管路防爆安全阀 Figure 9 The tube explosion-proof valve

当马达B口进油时卷扬进行放绳则选择图8所示阀块: 当马达A口进油时卷扬进行放绳则选择图9所示阀块。

备注: 防爆安全阀的安装方位至关重要,至于如何确定马达A侧、还是 B侧安装防爆安全,可参考:滚筒旋转方向说明。

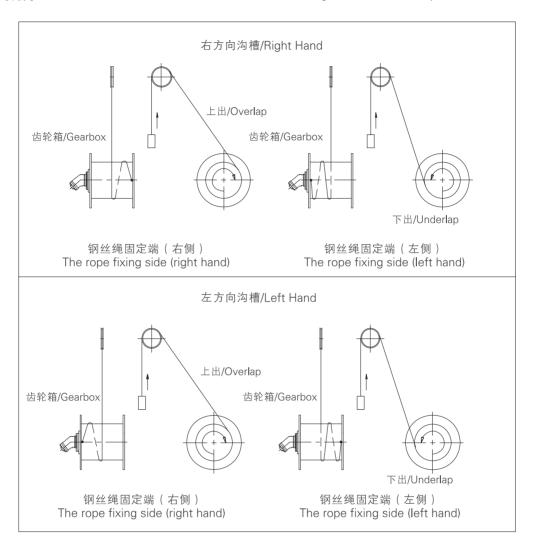
When filling the oil on motor B side and pull the rope, should select the valve as figure 8;

When filling the oil on motor A side and pull the rope, should select the valve as figure 9.

Remark: the tube explosion-proof valve mounting position is very important. How to confirm the mounting position is on the A side or B side of motor, you can refer to the winding direction on the rope drums.

5.3滚筒旋转方向说明

5.3 Winding direction on the rope drums.



钢丝绳方向 Rope direction	绳槽旋向 Rope groove lead	出绳方式 Rope pull mode	齿轮箱输出 Gearbox output	齿轮箱输入 Gearbox input	马达旋向 Motor rotation	马达进油口 Motor inlet oil port	平衡阀/防爆安全阀安装侧 Balance valve/ explosion-proof valve mounting position
	右方向/Right hand	上出绳/overshot	顺时针/CW	逆时针/CCW	顺时针/CW	A (B)	A (B)
18 (8 (5	右方向/Right hand	下出绳/undershot	逆时针/CCW	顺时针/CW	逆时针/CCW	B (A)	B (A)
提绳/Draw rope	左方向/Left hand	上出绳/undershot	顺时针/CW	逆时针/CCW	顺时针/CW	A (B)	A (B)
	左方向/Left hand	下出绳/undershot	逆时针/CCW	顺时针/CW	逆时针/CCW	B (A)	B (A)
	右方向/Right hand	上出绳/overshot	逆时针/CCW	顺时针/CW	逆时针/CCW	B (A)	A (B)
放绳/Release rope	右方向/Right hand	下出绳/undershot	顺时针/CW	逆时针/CCW	顺时针/CW	A (B)	B (A)
AX 2-E/TICIOUSC TOPC	左方向/Left hand	上出绳/overshot	逆时针/CCW	顺时针/CW	逆时针/CCW	B (A)	A (B)
	左方向/Left hand	下出绳/undershot	顺时针/CW	逆时针/CCW	顺时针/CW	A (B)	B (A)

- 备注: 1) 表中齿轮箱的输入输出方向定义为: 正对齿轮箱输入侧看。
 - 2) 表中液压马达旋转方向定义为:正对马达输出轴看。
 - 3) 滚筒方向定义为:正对马达齿轮箱输入侧看,滚筒方向即齿轮箱输出方向。
- Remark: 1) Gearbox output and input direction in above table: when facing the gearbox input shaft.
 - 2) The motor rotation in above table: when facing the motor output shaft.
 - 3) The drum rotation: When facing the gearbox input shaft, the gearbox output shaft rotation is the drum rotation.

6 选型说明

6.1使用说明

PW行星齿轮箱额定动态输出扭矩 $T_{\text{dyn max}}$ 按欧洲起重机械联合会标准FEM(FEM—Federation Europeenne de la Manutention)第三版第一章,驱动机构等级M5,负载分组L2(P=常数,=15rpm),工况等级T5分组设计。工作环境温度+20 $^{\circ}$ C。

如果卷扬机构分级为其它工作级别,则其所需输出扭矩 必须采用系数K进行修正。

T₂: 输出扭矩/output torque (N·m) Fnom: 单绳拉力/single rope pull (N)

Dw: 相应卷绕直径/rope strands diameter (m)

$$T_2 = \frac{\text{Fnom* Dw}}{2}$$

T_n: 修正后的输出扭矩/output torque with multiplied factor (N · m)

K: 工况系数(设备分组工况系数)/application factor (the relative factor for drive unit group and load conditions)

6 Type selection explanation

6.10peration instruction

temperature +20 °C.

 $T_{2k} = T_{2*}K$

注:齿轮箱选型时 T_{2k} 必须 \leqslant $T_{dvn\;max}$ (设计扭矩或样本扭矩) Note: T_{2k} \leqslant $T_{dvn\;max}$ (design torque or sample torque)

6.2工况系数(机构利用等级和载荷状态分级)

6.2Application factor K (running time classification and load conditions)

PW rated dynamic output torques $T_{dyn\ max}$ are based on FEM Standards section 1, 3rd edition (FEM – Federation Europeenne

de la Manutention). Drive unit group M5, load conditions L2 (P=constant, =15rpm), running time classification T5. Ambient

If the hoisting winch is classified as other working grades, the

output torque must be multiplied by the factor K.

	运行时间	级别/Symbol	T2	Т3	T4	T5	Т6	T7	Т8
工况等级 Running time	一年内,日平均 Mean running time per d	可工作时间(小时) ay in hours,related to one year	0.25至/to0.5	0.5至/to1	1至/to2	2至/to4	4至/to8	8至/to16	多于/over16
classification		1)8年,200天/年	400至/to	800至/to	1600至/to	3200至/to	6300至/to	12500至/to	25000至/to
	Life in hours 8 y	ears,200 days/year	800	1600	3200	6300	12500	25000	50000
负载情况 Load conditions	集合系数/Colled	ctive coefficient Km	设	备分组工》	兄系数/Driv	e unit clas:	s Applicat	tion Factor	K
L1	M	至/to0,125	M1	M2	M3	M4	M5	M6	M7
LI	log L	土/100.120	0.90	0.90	0.90	0.92	0.92	1.1	1.36
L2	M	0.125至/to0.250	M2	M3	M4	M5	M6	M7	M8
LZ	log L	0.123至/100.230	0.90	0.92	0.96	1	1.07	1.3	1.6
L3	М	0.250至/to0.500	МЗ	M4	M5	M6	M7	M8	M8
	log L	0,230±/100,300	1.05	1.09	1.17	1.23	1.28	1.53	1.89
L4	M	0.500至/to1.000	M4	M5	M6	M7	M8	M8	M8
L4	log L	0.500主/101.000	1.32	1.36	1.46	1.53	1.58	1.8	2.22

6.3起重机械典型载荷谱(图10)

6.3 Typical load spectrum for crane (figure 10)

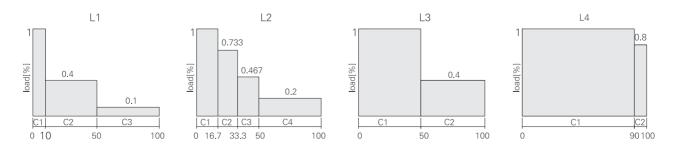


图10起重机械典型载荷谱 Figure 10 Crane load spectrum

6.4设备分级指导 参见FEM标准第三版第一章,表T.2.1.3.5 6.4Classification Guidance According FEM section 1, 3rd edition, table T.2.1.3.5

		table 1.2	. 1.0.0			
	工作元件		驱动机构	类型/Type of m	echanism	
起重机类型/Type of Crane (name)	Working accessories	起升 Hoisting	回转 Slewing	变幅 Luffing	小车运行 Traverse	大车运行 Travel
安装用起重机/Erection cranes		M2-M3	M2-M3	M1-M2	M1-M2	M2-M3
桥式起重机/Bridge crane	吊钩/Hook duty	M5-M6	M4	_	M4-M5	M5-M6
桥式起重机/Bridge crane	抓斗或磁铁 Grab or magnet	M7-M8	M6	-	M6-M7	M7-M8
车间用起重机/Workshop cranes	抓斗或磁铁 Grab or magnet	M6	M4	_	M4	M5
天车,夯锤起重机。废钢场起重机 Crane, Ram crane, Scrap mill crane	吊钩或磁铁 Hook or magnet	M8	M6	_	M6-M7	M7-M8
卸料桥,集装箱用门式起重机 Unloading bridge, Container gantry crane	吊钩/Hook	M6-M7	M5-M6	M3-M4	M6-M7	M4-M5
其它门式起重机(带小车和/或转台) Other gantry crane(with crab and/or slewing jib crane)	抓斗或磁铁 Grab or magnet	M4-M5	M4-M5	-	M4-M5	M4-M5
卸料桥,集装箱用门式起重机 (带小车或转台) Unloading bridge, Container gantry crane(with crab and/or slewing jib crane)	吊钩/Hook	M8	M5-M6	M3-M4	M7-M8	M4-M5
船台起重机船坞起重机,拆卸用起重机 Shipyard crane, Dock crane, Disassembly crane		M5-M6	M4-M5	M4-M5	M4-M5	M5-M6
港口起重机(可转动,门式),浮式起重机,浮式起重架 Dockside cranes (slewing, on gantry, etc.), floating cranes and pontoon derricks	吊钩/ Hook	M6-M7	M5-M6	M5-M6	_	M3-M4
港口起重机(可转动,门式),浮式起重机,浮式起重架 Dockside cranes (slewing, on gantry, etc.), floating cranes and pontoon derricks	抓斗或磁铁 Grab or magnet	M7-M8	M6-M7	M6-M7	-	M4M5
浮式起重机和浮式起重架,用于非常高的负荷 (一般在100t以上) Floating cranes and pontoon derricks for very heavy loads (usually greater than 100 t)		M3-M4	M3-M4	M3-M4	-	-
甲板起重机/Deck cranes	吊钩/Hook	M4	M3-M4	M3-M4	M2	M3
甲板起重机/Deck cranes	抓斗或磁铁 Grab or magnet	M5-M6	M3-M4	M3-M4	M4-M5	M3-M4
塔式起重机用于建筑工地 Tower cranes for building		M4	M5	M4	M3	M3
门式塔架/ Derricks		M2-M3	M1-M2	M1-M2	-	-
铁路起重机,批准用于铁路维修 Railway cranes allowed to run in train		M3-M4	M2-M3	M2-M3	_	_
车辆起重机/Mobile cranes	吊钩/Hook	M3-M4	M3-M4	M2-M3	_	_

备注: 仅列出了卷扬机构的一些典型范围以供参考

Note: Above are only some typical applications for hoisting winch.

7 传动能力

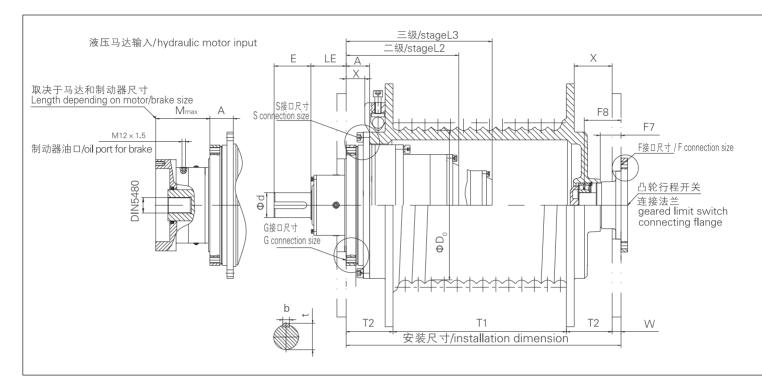
7 Transmission capacity

公称减速比 Nominal ratio	精确减速比 Exact ratio	型号/typePW	20	22	24	25	26	27	29	31	32	33	34	36	38	40																		
		T动/dynamic kN·m	11.6	19.4	25.5	36	48	63	105	155	236	311	406	644	1100	1500																		
i _N	i _{ex}	T静/static KN·m	18.5	31	41	57.5	77	101	168	248	377.5	497.5	649.5	1030.5	1760	2400																		
13	13.11		\Rightarrow	☆	☆	☆	☆	☆	☆	☆	☆																							
15	15.14		☆	☆	☆	☆	☆	☆	☆	☆	☆																							
18	18.22		\Rightarrow	☆	☆	☆	☆	☆	☆	☆	☆																							
20	20.45	2级/stage	☆	☆	☆	☆	☆	☆	☆	☆	☆																							
23	23.47		\Rightarrow	☆	☆	☆	☆	☆	☆	☆	☆																							
28	27.79		☆	☆	☆	☆	☆	☆	☆	☆	☆																							
45	44.97		$\stackrel{\wedge}{\Rightarrow}$	☆	☆	☆	☆	☆	☆	☆	☆																							
52	51.56		☆	☆	☆	☆	☆	☆	☆	☆	☆																							
59	59.10		☆	☆	☆	☆	☆	☆	☆	☆	☆																							
71	70.57		$\stackrel{\wedge}{\Rightarrow}$	☆	☆	☆	☆	☆	☆	☆	☆																							
79	78.88	3级/stage-	☆	☆	☆	☆	☆	☆	☆	☆	☆																							
84	84.23	Jax/Stage F	\Rightarrow	☆	☆	☆	☆	☆	☆	☆	☆																							
90	90.13		☆	☆	☆	☆	☆	☆	☆	☆	☆																							
105	105.18		☆	☆	☆	☆	☆	☆	☆	☆	☆																							
120	120.13		☆	☆	☆	☆	☆	☆	☆	☆	☆																							
141	141.49		☆	☆	☆	☆	☆	☆	☆	☆	☆																							
167	167.48		\Rightarrow	☆	☆	☆	☆	☆	☆																									
192	192.03		☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆																				
220	220.1		☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆																		
262	262.1		☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆																		
273	273.16	_										-	-	-							$\stackrel{\wedge}{\simeq}$	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆
293	292.54		$\stackrel{\wedge}{\Rightarrow}$	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆																		
313	312.95		☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	\Rightarrow	☆																		
334	333.74		\Rightarrow	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	\Rightarrow	☆																		
349	349.31		☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆																		
374	373.52		\Rightarrow	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆																		
393	392.59		\Rightarrow	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆																		
417	416.91		☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆																		
445	445.46	4级/stage	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆																		
476	475.62		\updownarrow	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆																		
509	508.98		☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆																		
532	531.54		☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆																		
559	559.49		☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆																		
594	593.94		☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆																		
625	625.27		☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆																		
678	678.38		☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	\Rightarrow	☆																		
699	698.68		☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆																		
798	798	[☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆																		
841	841.37		\Rightarrow	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆																		
940	939.89		\Rightarrow	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆																		

备注: 未注减速比请垂询!

Note: For ratios not listed, please contact!

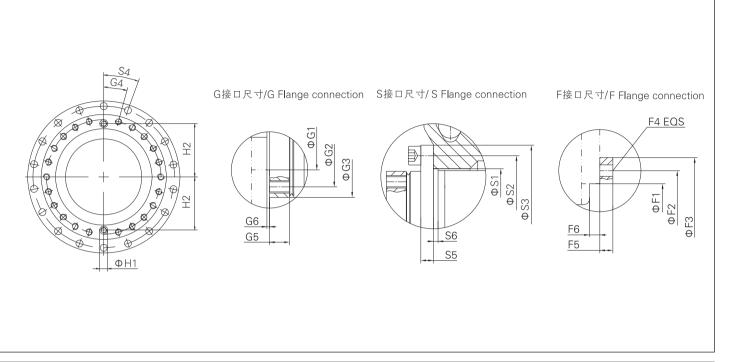
8 外形尺寸



		公称数据输出扭矩 Nominal Geatox ratings Cutruit roma (EX) m. 齿轮箱与钢结构连接螺栓强度等级1								S接口尺寸/S Flange connection						F接口尺寸/F Flange connection							
型号		t torque (KN.m) T静态	, 単绳				接螺栓强度等组 ame bolts clas						e螺栓强度等级 um Bolts class						网结构连接螺栓 inge to frame l				
Туре	单绳	最大	拉力	G1	G2	G3	G4	G5	G6	S1	S2	S3	\$4	S5	S6	F1	F2	F3	F4	F5	F6	F7	F8
PW	Tdyn max	Tstatic max	Fnom KN	止口 Location	分度圆 Pitch diameter	外径 outer diameter	分度 fixing			止口 Location	分度圆 Pitch diameter	外径 outer diameter	分度 fixing			止口 Location	分度圆 Pitch diameter	外径 outer diameter	分度 fixing				
20	11.6	18.5	69	200h7	255 ± 0.2	285	20° 16*M16	25	5	295h7	320 ± 0.2	340	15° 24* ↓ 14	12	9	175h7	200 ± 0.2	225	60° 6* φ11	15	10	30	64
22	19.4	31	98	230h7	280 ± 0.2	315	15° 22*M16	25	5	330h7	360 ± 0.2	390	20° 18*	16	9	200h7	230 ± 0.2	260	60° 6* ♦ 14	18	12	35	71
24	25.5	41	119	270h7	320 ± 0.2	355	15° 22*M16	25	5	370h7	400 ± 0.2	430	15° 24* φ 18	16	9	200h7	230 ± 0.2	260	60° 6* φ 14	18	12	35	71
25	36	57.5	147	300h7	350 ± 0 2	385	15° 22*M20	30	5	400h7	440 ± 0 2	480	20° 18* \(\phi \) 22	20	9	230h7	260 ± 0 2	290	60° 6* φ 18	18	15	40	78
26	48	77	184	330h7	390 ± 0.2	425	15° 22*M20	30	5	440h7	480 ± 0.2	520	15° 24* \(\phi \) 22	20	9	260h7	310 ± 0.2	360	60° 6* φ 22	25	15	50	92
27	63	101	220	355h7	420 ± 0.2	460	15° 22*M24	38	5	470h7	520 ± 0.2	560	20° 18* φ 26	24	9	260h7	310 ± 0.2	360	60° 6* φ 22	25	15	50	92
29	105	168	313	430h7	480 ± 0.2	530	15° 22*M24	38	5	550h7	590 ± 0.2	630	15° 24* φ 26	24	9	300h7	350 ± 0.2	400	60° 6* φ 22	30	15	50	104
31	155	248	408	515h7	565 ± 0.2	615	15° 24*M30	47	5	640h7	690 ± 0.2	750	15° 24* φ 33	30	9	325h7	375 ± 0.2	425	60° 6* φ 26	35	15	70	134
32	236	377.5	566	580h7	630 ± 0.2	680	15° 24*M30	47	5	700h7	755 ± 0.2	815	15° 24* φ 33	30	9	325h7	375 ± 0.2	425	60° 6* φ 26	35	15	70	134
33	311	497.5	660	670h7	720 ± 0.2	770	12° 30*M30	47	5	790h7	840 ± 0.2	890	12° 30*	30	9	375h7	435 ± 0.2	500	60° 6* φ 33	40	15	80	144
34	406	649.5	787	720h7	770 ± 0.2	820	10° 36*M30	47	5	850h7	900 ± 0.2	950	36* \phi 33	30	9	375h7	435 ± 0.2	500	60° 6* φ 33	40	15	80	144
36	644	1030.5	1073	840h7	900 ± 0.2	960	10° 36*M36	56	5	1000h7	1055± 0.2	1120	10° 36* ⊕ 39	36	9	430h7	490 ± 0.2	550	60° 6* ф 33	40	15	90	180
38	1100	1760	1520	1060h7	1140 ± 0.2	1210	10° 36*M30	78	26	1240h7	1320±0.2	1390	10° 36* ф 33	45	13	600h7	680 ± 0.2	750	30° 12*	50	20	80	180
40	1500	2400	1950	1160h7	1240 ± 0.2	1310	10° 36*M30	78	26	1340h7	1420± 0.2	1490	10° 36*	45	13	600h7	680 ± 0.2	750	30° 12*	50	20	80	180

备注: 未注尺寸请垂询

8 Dimension Drawing



安装尺寸/installation dimension 轴(电机)输入/shaft (motor) input																								
2: d	级/stag E			ベ/snant 级/stag		ı. I	级/stag	ge LE	液压 马达 输入 hydraulic motor input	A	 2级/stage	- 347/stage	T1m		D ₀	χ	T2	W 推荐	油管: oil pump o	connection	重 2级/stage	量/weig (kg) 3级/stage		型号 Type PW
u	_		ч	_		ď			Mmax		L2	L3	LJX/ Jugo	0-3X/ 3 tage	min	min		suggestion	111	112	Lyx, ougo	0-9X/ 0 0ug0	13X/ 300g0	PW
55m6	110	98.5							183	60	300		240		340	15	95	15	26	117	120			20
55m6	110	85							171	60	315		255		390	15	100	15	26	132	140			22
75m6	140	135.5	65m6	140	117.5				207	60	350	489	290	430	440	20	100	20	26	152	210	245	—	24
75m6	140	118	65m6	140	100				189	75	366	506	295	435	480	20	120	20	30	168	245	275		25
95m6	170	139.5	65m6	140	104.5	65m6	140	238	209	75	426	555	355	480	520	20	120	20	30	184	365	385	415	26
95m6	170	135	65m6	140	100	65m6	140	233.5	204	90	431	560	345	475	570	20	140	20	30	195.5	400	415	445	27
110m6	210	165	95m6	170	165	75m6	140	281	209	90	507	685	420	595	670	25	145	25	30	233	630	720	730	29
110m6	210	142	95m6	170	142	75m6	140	258	186	110	530	708	425	600	770	30	180	30	38	235	805	890	920	31
			110m6	210	130	75m6	140	251	321	110		800		695	830	30	180	30	38	268		1320	1360	32
_						110m6	210	381	462	110		928		820	930	40	180	40	38	298	_		1970	33
—	—					110m6	210	377.5	458	120		932		815	1030	40	200	40	38	335	—	—	2195	34
						110m6	210	264	345	120		1045		970	1200	50	240	50	38	385			2920	36
						160m6	300	421	457	130		1415		1320	1360	50	240	60	45	497			6650	38
						160m6	300	392	307	130		1444		1650	1530	50	240	60	45	545			7660	40

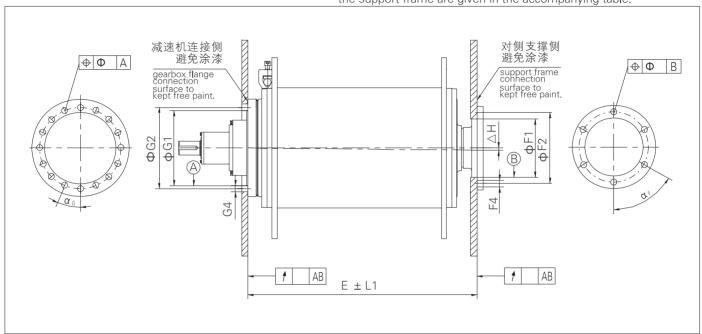
Note: For dimensions not listed, please contact!

9 安装规则

为了保证卷扬机的正常运转,卷扬齿轮箱与支撑钢结构的安装孔必须对中,并且法兰安装面必须与其垂直。钢结构安装孔与法兰安装面之间的相对位置在工作中、环境影响及外力作用下不允许有过大的改变。卷扬机支撑钢结构的制造公差及允许的最大变形见下表。

9 Assemble method

To ensure correct operation of the winch, the winch gearbox must be in the same line with the frame fixing hole centers and the flange pieces square to the base plate. The relative location between frame mounting central hole and flange mounting surface shouldn't be changed more when they are operating in different environment and outer force. The working tolerance and allowed max. deflections for the support frame are given in the accompanying table.



型号 Type		首连接侧 ox flange nection	l	对侧支撑侧 support frame connection 				组装长度L1上中轴线的最大允许偏差△H Maximum permitted deviation Δ H from the central line in relation to L1							
PW	f AB	ФФА	αg	↑ AB	ФВ	α_{F}	L1	250	500	750	1000	1500	2000	2500	PW
20	0.1	0.4	20°	0.2	0.3	60°	2	0.1	0.2	0.2	0.3	0.4			20
22	0.1	0.4	15°	0.2	0.3	60°	2		0.2	0.2	0.3	0.4			22
24	0.1	0.4	15°	0.2	0.3	60°	2			0.2	0.3	0.4	0.5		24
25	0.1	0.5	15°	0.4	0.5	60°	2			0.2	0.3	0.4	0.5		25
26	0.1	0.5	15°	0.4	0.5	60°	3			0.2	0.3	0.4	0.5		26
27	0.1	0.5	15°	0.4	0.5	60°	3				0.3	0.4	0.5		27
29	0.1	0.5	15°	0.4	0.5	60°	3				0.3	0.4	0.5		29
31	0.2	0.5	15°	0.6	0.5	60°	3				0.3	0.4	0.5		31
32	0.2	0.5	15°	0.6	0.5	60°	3				0.3	0.4	0.5	0.7	32
33	0.2	0.5	12°	0.6	0.5	60°	3				0.3	0.4	0.5	0.7	33
34	0.2	0.5	10°	0.6	0.5	60°	3				0.3	0.4	0.5	0.7	34
36	0.3	0.5	10°	0.8	0.5	60°	3				0.3	0.4	0.5	0.7	36
38	0.3	0.5	10°	0.8	0.5	30°	3					0.4	0.5	0.7	38
40	0.3	0.5	10°	0.8	0.5	30°	3					0.4	0.5	0.7	40

10 润滑说明

润滑油(重负荷工业齿轮油)粘度牌号选用【VG320(附件 Lubrication viscosity (heavy industrial gear oil) [VG20 代号:UV32);VG460(附件代号:UV46)】

10 Lubrication

(Code: UV32); VG460 (Code: UV46)]

环境温度/Ambient temperature℃	-20°C ~ +40°C	+30°C ~ +50°C
粘度牌号/Viscosity	VG320	VG460

注: 1.支撑结构轴端轴承采用脂润滑。

- 2.上表中粘度牌号为40℃温度下的ISO-VG粘度。
- 3.环境温度低于-10℃必须使用合成油。
- 4.为保证产品寿命,实际使用中建议使用合成油。
- 5.若环境温度超出上述范围,敬请垂询。
- Note: 1. The bearing on the support frame is lubricated by grease.
 - 2. Above table viscosity is only for the temperature under 40°C_o
 - 3. Ambient temperature is -10°C, must use synthetic oil.
 - 4. To make sure the long using life, we suggest to use synthetic oil.
 - 5. If the ambient temperature is not in the range of table, please consult BONENG.

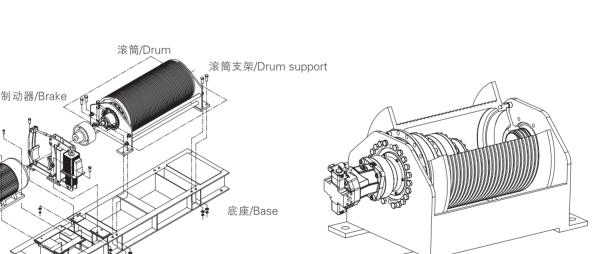
11 附件(具体请垂询)

11 Accessories (on request)

- □ 滚筒 (光筒、普通沟槽、特殊沟槽) /Drum (without grooves, with normal grooves, with special grooves)
- □ 滚筒支架/Drum support
- □ 底座/Base plate
- □ 电机/Motor
- □ 液压马达/Hydraulic motor
- □ 制动器/Brake
- □ 阀块/Valve

电机/Moto

□ 编码器/Encoder



电机驱动总成 Integrated motor drive

液压马达驱动总成 Integrated hydraulic motor drive

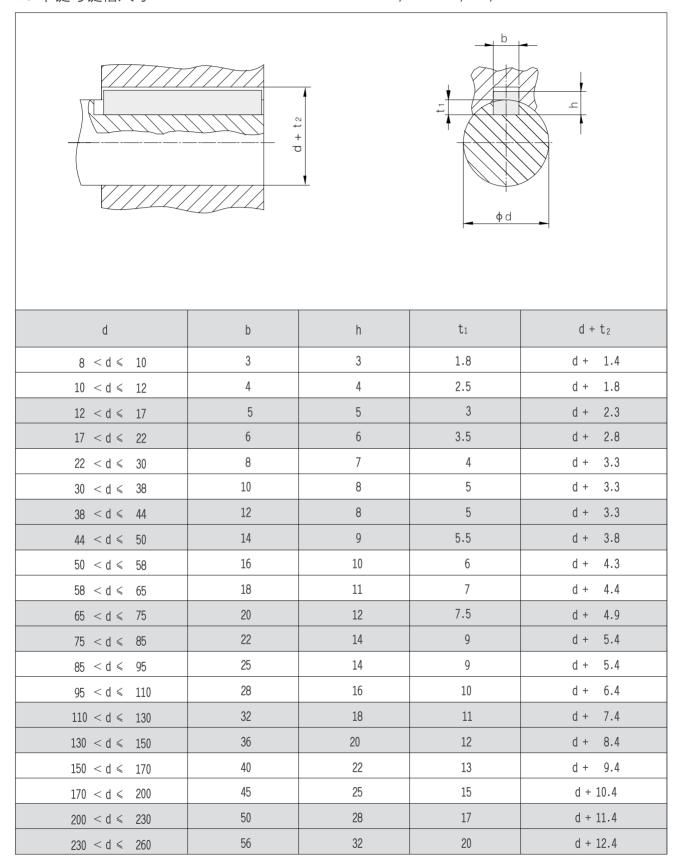
12 轴端中心孔:

12 Shaft end central hole:

轴端C型螺纹中心孔/C type screw central hole 120_° 60 Μ L 12 11 D1 D2 $7 < d \le 10$ М3 2.6 3.2 5.8 10 1.8 $10 < d \le 13$ 7.4 M4 10 3.2 2.1 4.3 $13 < d \le 16$ M5 10 4 2.4 5.3 8.8 $16 < d \leq 21$ M6 12 5 2.8 6.4 10.5 $21 < d \leq 24$ M8 6 13.2 12 3.3 8.4 24 < d ≤ 30 M10 15 7.5 3.8 10.5 16.3 30 < d ≤ 38 19.8 20 9.5 4.4 13 M12 $38 < d \leq 50$ M16 17 25.3 $50 < d \le 85$ M20 30 15 6.4 31.3 21 $85 < d \leq 130$ 8 38 M24 35 18 25 $130 < d \le 225$ M30 45 18 11 31 48

13 平键与键槽尺寸

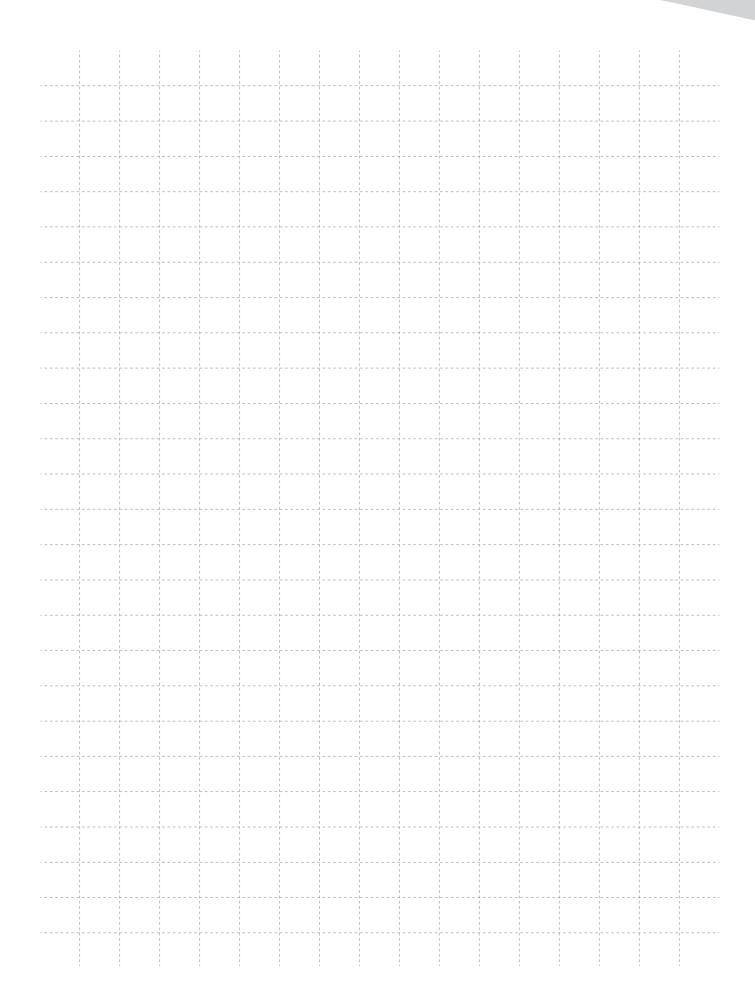
13 Key and Keyway dimension

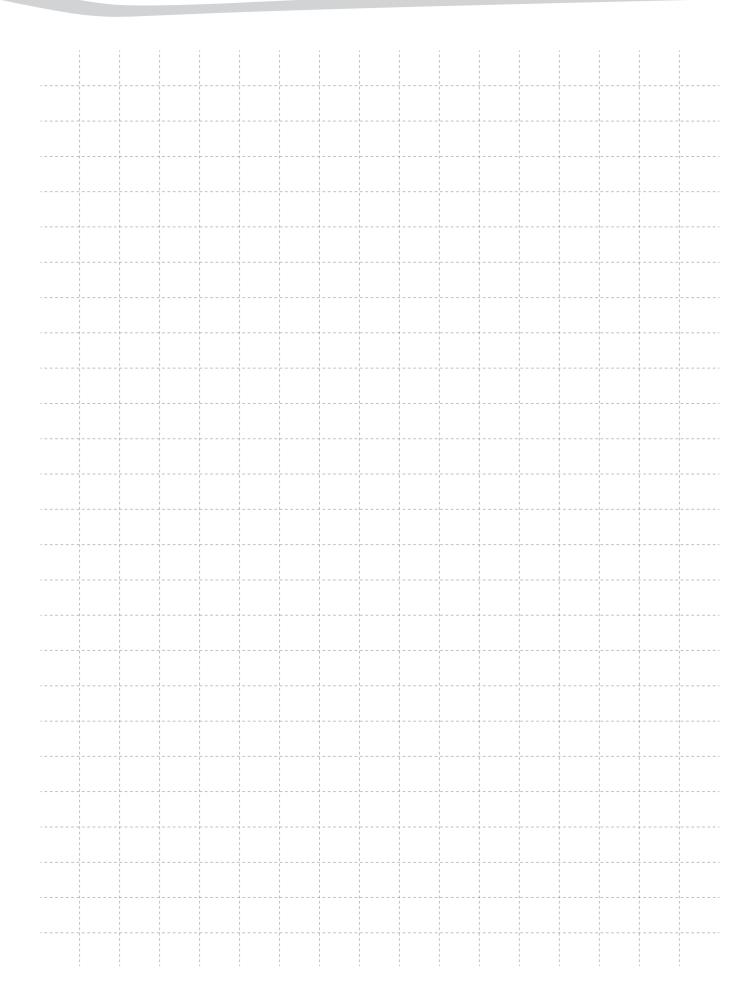


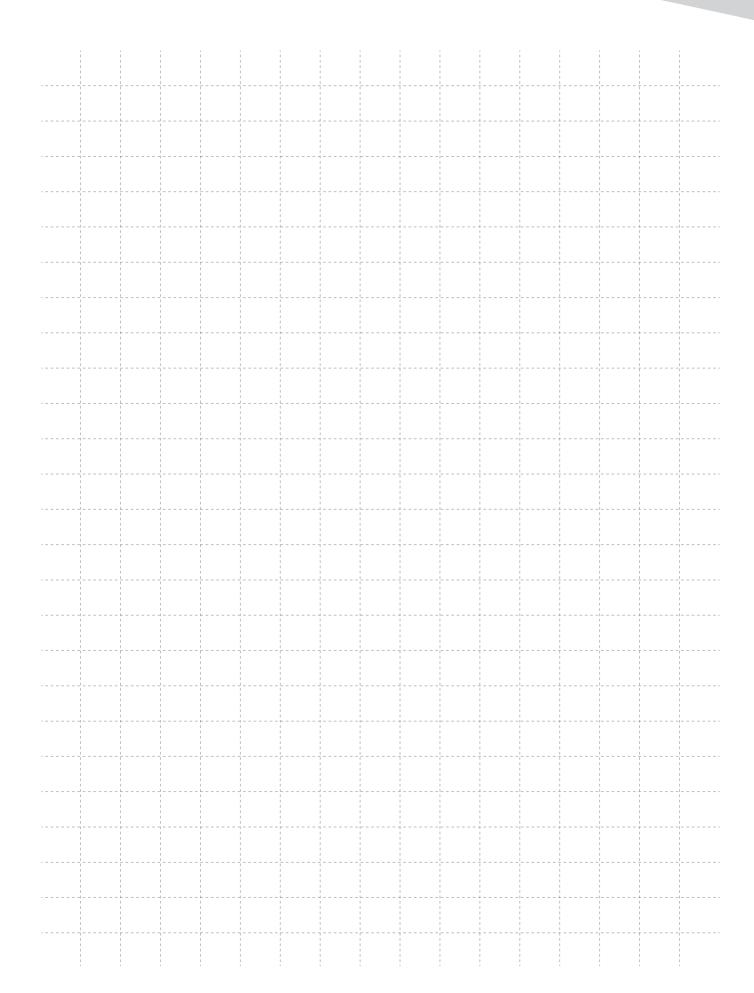
14 设计参数表 14 Parameter table 公司名称/Company name: 地址/Address: 联系人/Contact: 电话/Tel: 传真/Fax: 应用/Application: (举例/e.g. 岸桥/Quay crane, 克令吊/crane, 汽车吊/mobile crane,船载起重等/ship offshore harbor cranes etc.) _____ (举例/e.g. 主卷扬/Hoisting, 副卷扬/luffing, 牵引机/pulling winch) 用于/Used for: 技术参数/Technical data 工况概述/Operating condition 卷筒直径/Diameter of rope drum: [mm] [KN] 卷筒上拉力(第一层)/Drum over pull (first rope layer)F1: (第一层/first rope layer) 最外层拉力/Top rope layer line pull F2: [KN] 钢丝绳直径/Rope diameter d: [mm] 最大测试载荷第() 层/Max. testing loading number of rope layer F: [KN] 卷筒螺旋方向/Drum lead:: □ 右/right □ 左/left 额定载荷下绳的速度/Rope speed with rated loading V: [m/min] □ 普通绳槽/normal groove □ 特殊绳槽/special groove 空载时绳的速度/Rope speed without loading V: [m/min] □ 光筒/grooveless 卷筒上绳的数量/Rope numbers on the drum n: [KN] 钢丝绳固定位置/Position of rope anchor: 卷筒上总的绳拉力/Total line pull at drum F: □ 齿轮箱驱动端/drive side 钢丝绳长度/Rope length Ls: [mm] □ 齿轮箱驱动端对面/opposite to drive (including 3 safety turns) 速比/Ratio i: 卷筒长度或两档板间距/Length of drum between flanges L2: [mm] 分类按/Classify as FEM1.001---ISO4301 设备分组/Drive unit group M: 起重等级/The load spectrum L: 工作时间等级/Running time classification T: 驱动单元/Drive unit □电机驱动/electric motor drive: □ 液压马达驱动/hydraulic motor drive 型号/Type: 型号/Type: 功率/Power P: _____ [KW] 有效流量/Available oil flow q_v: _____ [L/min] 额定转速/Rated speed n: _____[rpm] 有效压力差/Available pressure difference△P: _____[bar] 排量/Displacement V_a : ______[cm³] 起动转矩/Starting torque MA: _____[Nm] 极限转矩/Breakdown torque Tk: _____[Nm] 每小时起动/Starting per hour: 制动/Brake 应用类型/Actuation □ 液压/hydraulically 类型/Apply as □ 驻车制动/parking brake 工作压力最小/Min. release pressure——— [bar] 工作压力最大/Max. release pressure_____[bar] □ 电力/磁力electric/ magnetic □ 工作制动/service braking 目前供货范围(具体请垂询)/Scope of supply (on request)

□ 齿轮箱/gearbox	□ 液压马达/hydraulic motor
□ 滚筒支架/drum support	□ 制动器/brake
□ 滚筒/drum	□ 阀块/valve
□ 电机/motor	□ 编码器/encoder

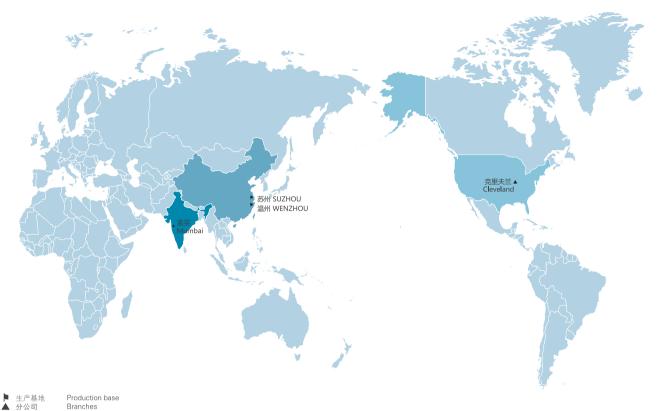
备注和特殊要求/Remarks and special requests:______







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